

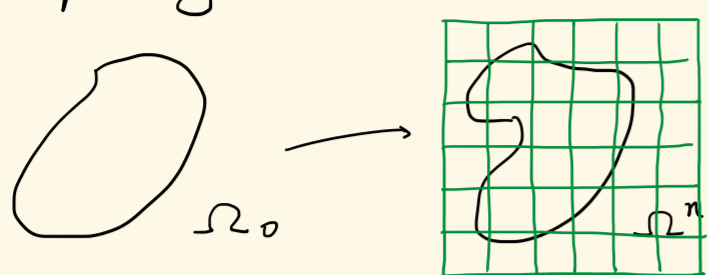
PDE:  $R \cdot \frac{\partial v}{\partial t} = \nabla^x \cdot p + R \cdot g, \quad X \in \Omega, t \in (0, T)$

where,  $p =$  first Piola-Kirchhoff stress

$= J \sigma F^{-T}$  ( $\sigma$ : Cauchy stress,  $J = \det(F)$ ,  $F = \frac{\partial \phi}{\partial X}$ )

FEM

- $t > t^n$ , assume we know  $\phi: \Omega \times [0, t^n]$
- interpolating function



- chose interpolating function  $N_i$  over grid.
- e.g. B-spline (Q1. How?) ( $N_i: \Omega^n \rightarrow \mathbb{R}$ ) (on grid)
- define:  $\hat{N}_i(X) = N_i \circ \phi(X, t^n)$  ( $\hat{N}_i: \Omega^n \rightarrow \mathbb{R}$ )

Then, do FEM in standard way.

$\phi(X, t) = \sum_i x_i(t) \hat{N}_i(X), t > t^n$

$\Rightarrow$  weakform (discrete)

$\int_{\Omega^n} (w_i \hat{N}_i)^T R \cdot \frac{\partial \phi}{\partial t} dX = \int_{\Omega^n} (w_i \hat{N}_i)^T \nabla^x \cdot p dX + \int_{\Omega^n} (w_i \hat{N}_i)^T R \cdot g dX$

$\Downarrow$   
 $w_{i\alpha} \int_{\Omega^n} \hat{N}_i R \cdot \hat{N}_j dX \cdot \frac{\partial x_{i\alpha}}{\partial t} = w_{i\alpha} \int_{\Omega^n} \hat{N}_i \frac{\partial p_{\alpha\beta}}{\partial X_\beta} dX + w_{i\alpha} \int_{\Omega^n} R \cdot \hat{N}_i g_\alpha dX$

or:  $w_{i\alpha} \underbrace{M_{i\alpha j \beta}}_{\textcircled{1}} \frac{\partial x_{i\alpha}}{\partial t} = w_{i\alpha} \int_{\Omega^n} \frac{\partial}{\partial X_\beta} (\hat{N}_i p_{\alpha\beta}) - p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial X_\beta} dX + w_{i\alpha} \int_{\Omega^n} R \cdot \hat{N}_i g_\alpha dX$   
 $= w_{i\alpha} \left( \int_{\partial \Omega^n} \hat{N}_i p_{\alpha\beta} N_j dS - \int_{\Omega^n} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial X_\beta} dX \right) + w_{i\alpha} \int_{\Omega^n} R \cdot \hat{N}_i g_\alpha dX$

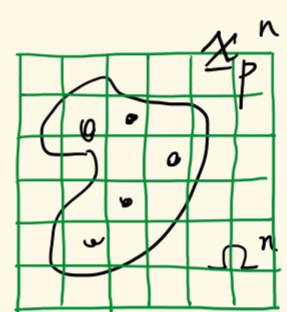
Now let's change variable and integrate over  $\Omega^{tn}$  (Q2. what's this? is this the normal vector or the interpolating function? (normal))

①.  $M_{i\alpha j \beta} = \int_{\Omega^n} \hat{N}_i R \cdot \hat{N}_j dX \cdot \delta_{\alpha\beta}$   
 $= \int_{\Omega^{tn}} N_i R(\phi^{-1}(x, t^n), t^n) N_j \frac{1}{J^n} dx \cdot \delta_{\alpha\beta}$   
 $= \int_{\Omega^{tn}} N_i \rho(x, t^n) N_j dx$  (where  $\rho(x, t^n) = R(x, 0) / J(x, t^n)$ )

②.  $\int_{\Omega^n} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial X_\beta} dX$   
 $= \int_{\Omega^{tn}} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial X_\beta} \circ (\phi^{-1}(x, t^n)) \frac{1}{J^n} dx$   
 $= \int_{\Omega^{tn}} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial x_\gamma} f_{\gamma\beta}(x, t^n) \frac{1}{J^n} dx$   
 $= \int_{\Omega^{tn}} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial x_\gamma} f_{\gamma\beta}(x, t^n) \frac{1}{J^n} dx$

Introduce quadratic

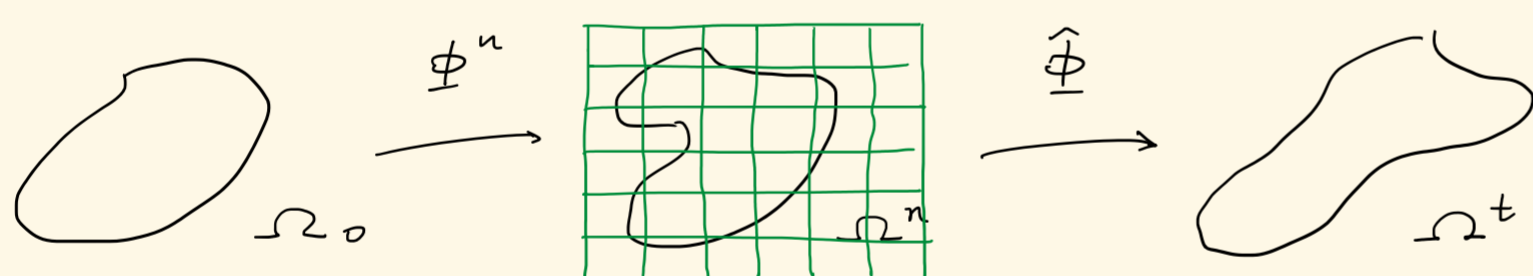
①.  $M_{i\alpha j \beta} \approx \sum_p N_i(x_p) \rho(x_p, t^n) N_j(x_p) V_p^n$   
 $= \sum_p N_i(x_p) m_p^n N_j(x_p)$   
 (  $V_p^n = J_p^n V_p^0$ ,  $m_p^n = R^n(x_p) V_p^n$  )



②.  $\int_{\Omega^n} p_{\alpha\beta} \frac{\partial \hat{N}_i}{\partial X_\beta} f_{\gamma\beta} \frac{1}{J^n} dx$   
 $\approx \sum_p p_{\alpha\beta}(x_p, t) \frac{\partial N_i}{\partial x_\gamma}(x_p^n) F_{\gamma\beta}(x_p, t^n) \frac{1}{J_p^n} V_p^n$

e.g. Hyperelastic:

$p_{\alpha\beta}(x_p, t) = \frac{\partial \psi}{\partial F_{\alpha\beta}}(F(x_p, t))$   
 ( since  $\phi(x, t) = \sum_i \hat{x}_i(t) N_i(\phi(x, t^n))$   
 $= \hat{\phi}(\phi(x, t^n), t)$   
 we have:  $\frac{\partial \phi}{\partial X} = \frac{\partial \hat{\phi}}{\partial X}(\phi(x, t^n), t) \cdot F(x, t^n)$   
 $= \hat{F} \cdot F^n$  )



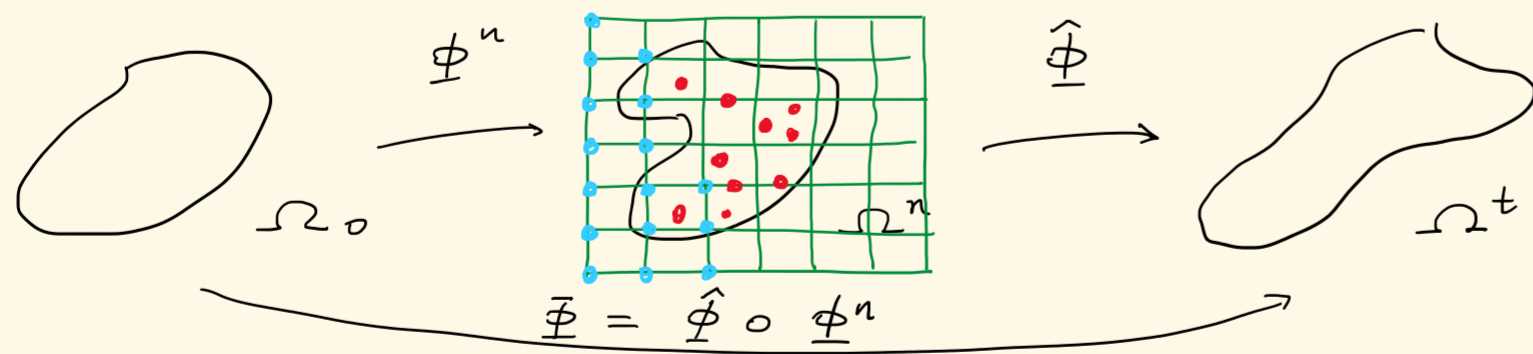
$\Rightarrow p_i(x_p, t) = \frac{\partial \psi}{\partial F} \left( \left[ \sum_j \hat{\phi}_j(t) \frac{\partial N_i}{\partial X}(x_p^n) \right] F_p^n \right)$

Thus,

$R \cdot \frac{\partial \phi}{\partial t} = \nabla^x \cdot p + R \cdot g$  (for cauchy static problem)  
 (Q3: I forget what is this line stands for ...)

Now we have:

$\phi(x, t) = \sum_i \hat{\phi}_i(t) N_i \circ \phi(x, t^n)$   
 $\frac{\partial \phi}{\partial t}(x, t) = \sum_i \frac{\partial \hat{\phi}_i(t)}{\partial t} N_i \circ \phi(x, t^n)$   
 $M_{i\alpha j \beta} \frac{\partial \hat{\phi}_i}{\partial t}(t) = - \sum_p p_{\alpha\beta}(x_p, t) \frac{\partial N_i}{\partial x_\gamma}(x_p^n) F_{\gamma\beta}(x_p, t^n) V_p^0 + \sum_p m_p N_i(x_p^n) g_\alpha$



We use  $\bullet$  to have  $\bullet$ ,  
 $M_{i\alpha j \beta} = \sum_p m_p N_i(x_p^n) N_j(x_p^n) \delta_{\alpha\beta}$ .

Do backward Euler

$M_{i\alpha j \beta} \left( \frac{\hat{\phi}_{i\beta}^{n+1} - \hat{\phi}_{i\beta}^n}{\Delta t} - v_j^n \right) = - \sum_p p_{\alpha\beta} \left( \hat{\phi}_i^{n+1} \frac{\partial N_i}{\partial X}(x_p^n) \right) F_{\alpha\beta} \frac{\partial N_i}{\partial x_\gamma}(x_p^n) V_p^0 + \sum_p m_p N_i(x_p^n) g_\alpha$

\* Note:  $\hat{\phi}_j(t^n) = \hat{x}_j = x_j \leftarrow$  location of  $j$ -th grid node  
 e.g. when  $t = t^n$ ,  $\hat{\phi} = I$

- at last, we need  $v_j^n$ .
- (around we have  $v_p^n$  on portside)
- $v_j^n \approx \sum_p m_p v_p^n N_j(x_p^n) / m_j^n$  (grid node mass)
- (  $m_j^n = \sum_p m_p N_j(x_p^n)$  )

Solve with Newton method, etc. We'll get  $\hat{\phi}_j^{n+1}$ .

then we know  $\hat{\phi}(x, t^{n+1}) = \hat{\phi}_j^{n+1} N_j(x)$   
 and let's interpolate motion to the pectifs.

$x_p^{n+1} = \hat{\phi}_j^{n+1} N_j(x_p^n)$   
 $v_p^{n+1} = \frac{(x_j^{n+1} - x_j^n)}{\Delta t} N_j(x_p^n)$  \* less angular momentum.  
 $v_p^n = \frac{(x_j^{n+1} - x_j^n)}{\Delta t} - v_j^n$   $N_j(x_p^n) + v_p^n$   
 this can greatly reduce the angular momentum loss.  
 $F_p^{n+1} = \hat{\phi}_j^{n+1} \frac{\partial N_j}{\partial X}(x_p^n) \cdot F_p^n$